

# TECHNICAL NEWS

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## IMPROVING STAR-DELTA PROTECTION

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There are several options when providing overload and short circuit protection for a star-delta motor starter. Understanding these options can provide improved protection of the motor and in some cases can permit a reduction in cable size. The cable must be provided with both short circuit and overload protection. The requirements for this protection are covered by the Wiring Rules (AS/NZS 3000:2000).

### 1. Protection of motors with direct-on-line starting

A normal three-phase motor is sufficiently protected by the combination of a contactor and a circuit breaker with motor protective characteristic. As the full rated current of the motor flows through the circuit breaker, the current setting of the thermal release is equal to the motor rated current. The cables are rated according to the motor current / circuit breaker setting.

### 2. Protection of motors with star-delta starting

#### 2.1 With one circuit breaker

In the case of a star-delta starter, the upstream circuit breaker can takeover the motor protective function and thermal overloads fitted to the contactors are not required. The circuit breaker also provides the overload and short circuit protection

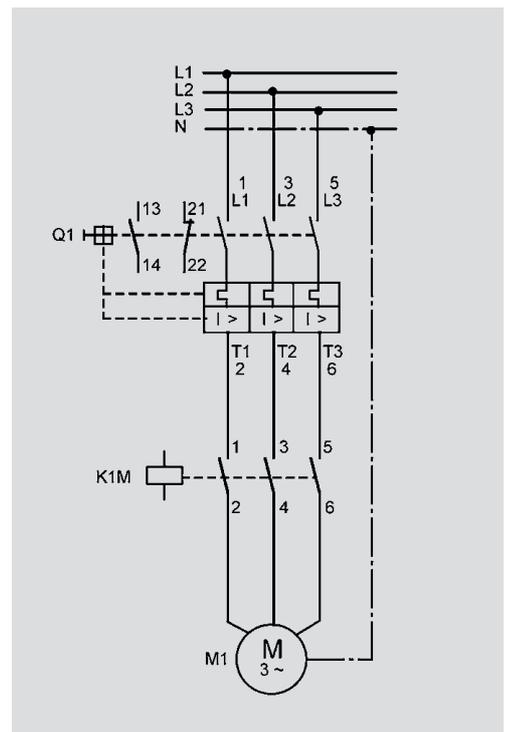
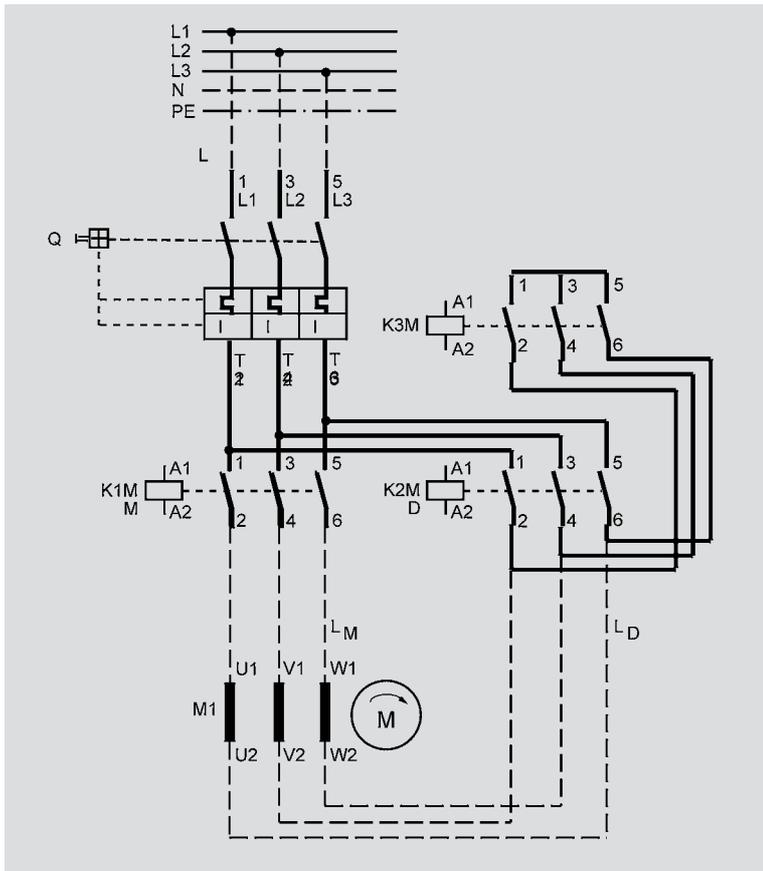


Fig. 1: Starter for direct-on-line starting with circuit breaker

required for the cables. The cross-section of the connecting leads to the motor must be selected on the basis of the current setting of the circuit breaker for overload protection and for short circuit protection the energy let through of the circuit breaker during a fault. The current setting of the thermal release of the circuit breaker (motor protection style) is to be equal to the actual rated current of the motor.



- Basic Protection **1**
- Protecting The Cables **2**
- Dual Circuit-Breakers **3**



**Fig. 2:** Starter for star-delta starting with one circuit breaker

breaker would be say 1.2 times the motor rated current. A distribution type circuit breaker could also be used with a suitable current setting to prevent it tripping before a thermal overload.

As cable thermal overload protection is now provided for a current of 0.58 times  $I_e$  the cables can be selected on this basis. For long cable runs this can produce a worthwhile saving. In addition the motor is now protected against failure of the starter to sequence to delta.

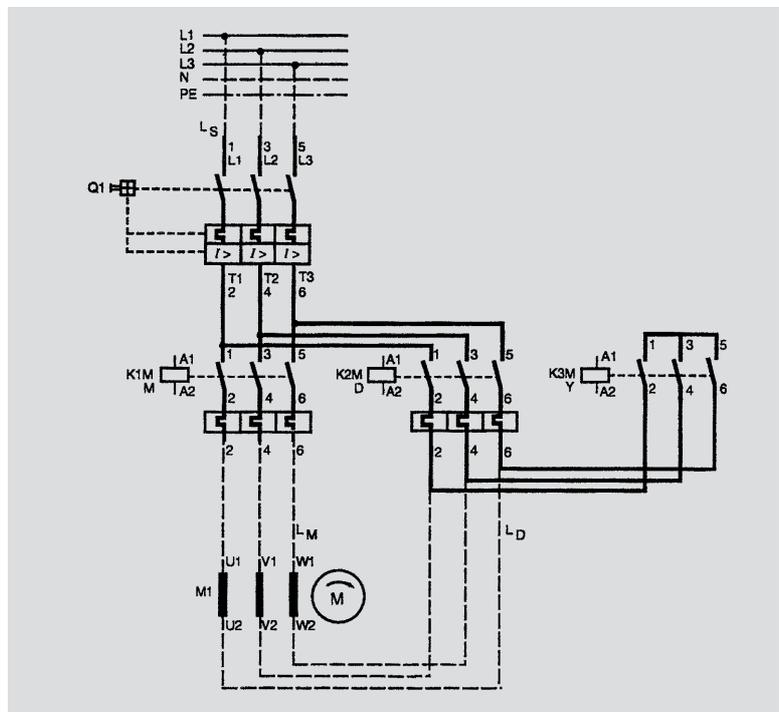
While the same protection would be provided with one thermal overload relay the Wiring Rules requirements suggest two would be required to take advantage of the possible reduction in the size of both  $L_M$  and  $L_D$  cables.

The six connecting wires however, will normally only carry  $0.58 \times$  rated motor current ( $I_e$ ). A cable ( $L_M$  and  $L_D$ ) selected for this current would be protected against overload in run or delta connection but not in the star connection, so it must be rated for the full motor current.

If the starter fails to change over from star to delta the motor can run with the windings overloaded without the circuit breaker detecting an overload. The current needs to exceed 1.7 times the rating of the winding before it starts looking like an overload.

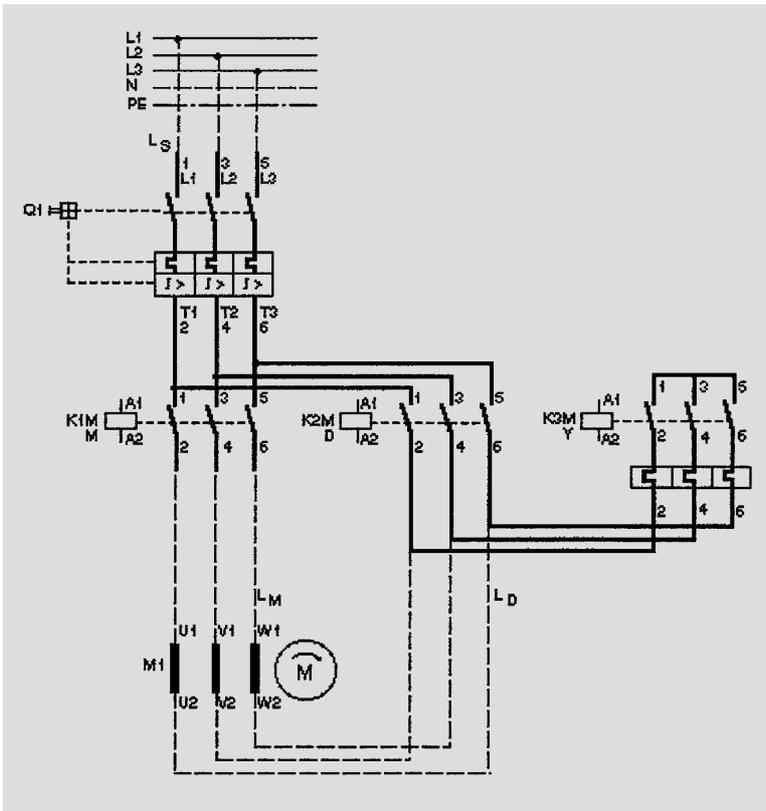
## 2.2 With one circuit breaker and two thermal overload relays

For economical reasons, it can be justifiable to use even two thermal overload relays in the motor winding circuits to realise



**Fig. 3:** Starter for star-delta starting with one circuit breaker and two thermal overload relays

a reduction of the cross-section of the motor connecting leads. The current setting of the thermal overload relays would be 0.58 times  $I_e$  whereas the setting of the current dial of the circuit



**Fig. 4:** Starter for star-delta starting with one circuit breaker and one additional thermal overload relay in series with the star-contactor during the running-up phase.

current in delta-connection ( $0.58 \times I_e$ ). The relay should be connected to control K1M and not K3M. The relay could also be fitted to K1M and remain in circuit after the initial star connected run up but in this position it is less suitable for heavy duty starting.

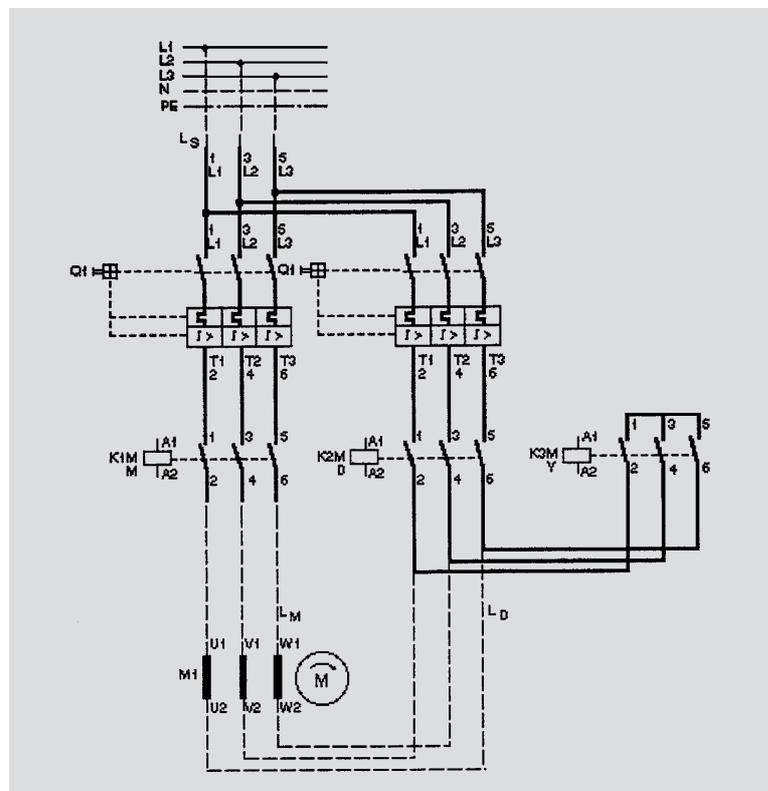
## 2.4 With two circuit breakers

A star-delta starter with two circuit breakers permits a reduction in the cross section of the motor connecting leads and is suitable for heavy-duty

## 2.3 With one circuit breaker and one thermal overload relay

During the period when the starter is connected in star, the current is equal to one third of what would flow in the delta connection. The current setting of the circuit breaker is, however, equal to  $I_e$ . If the rotor is locked during starting, a current of about twice  $I_e$  may flow through the circuit breaker. Thus, the circuit breaker will trip with a relatively long time delay in the case of locked-rotor during starting. This may damage the motor.

Fitting an additional thermal overload relay connected in series with the star-contactor takes over the protective function during the run-up phase of the motor. The maximum current setting of this relay should be equal to the phase



**Fig. 5:** Starter for star-delta starting with two circuit breakers for reduced cross-section of the motor connecting leads and suitable for heavy-duty starting.

# 4

starting with relatively long run up time.

The current setting of the breakers would normally be 0.58 x I<sub>e</sub>, but for heavy duty starting the circuit breaker connected above K1M can have a higher setting to allow a longer run up time. The cables L<sub>M</sub> would need to be sized to this setting.

## 3. Conclusion

The placement of the protection on a star delta starter can give

varying degrees of protection and also alter the permissible minimum cable sizes. In critical applications and in cases of long cable runs careful consideration should be given to the protection arrangement. Some advanced electronic relays can allow for the change from star to delta and may permit the use of cables based on the smaller currents inside the delta loop.

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